

# Bayesian Decision Theory

Krithika Venkataramani

# Salmon and Sea Bass



Salmon

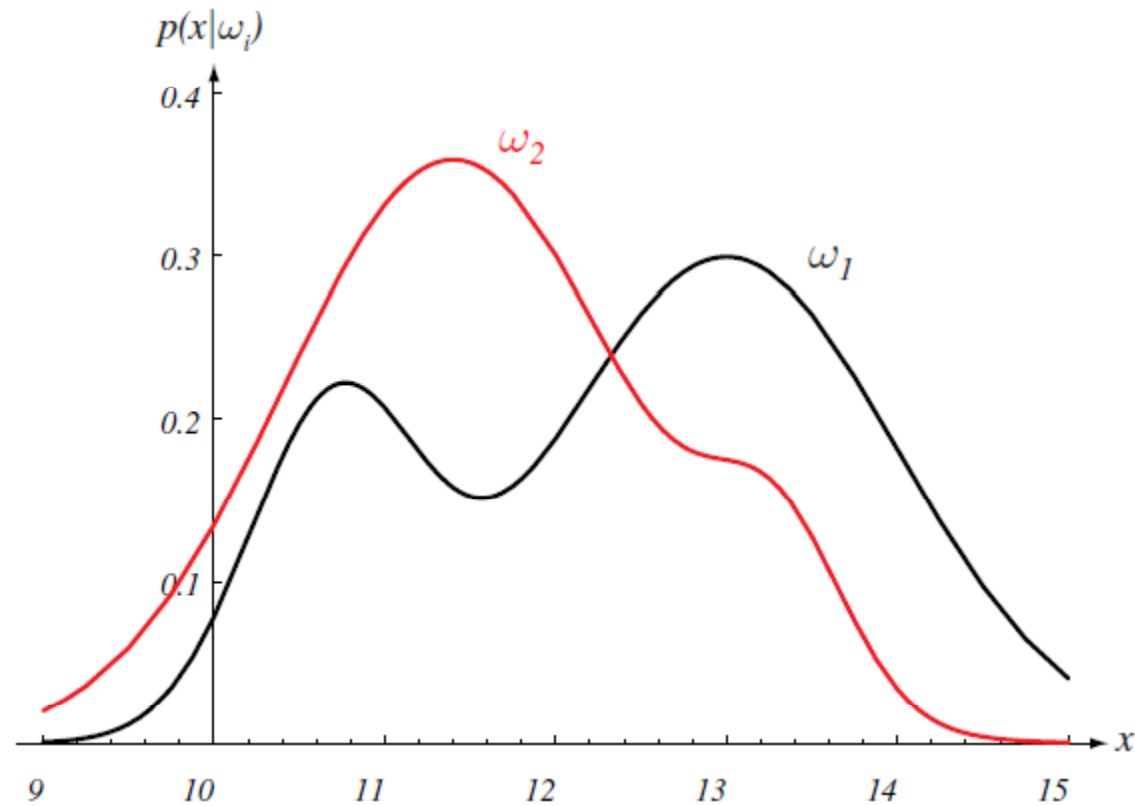


Sea Bass

# Deciding between Sea Bass and Salmon

- Separate salmon and sea bass on a conveyor present in a fish packing plant
- State of nature:  $\omega = \omega_1$  for sea bass and  $\omega = \omega_2$  for salmon
- A priori probability: based on the relative numbers in catch
- If there are no other fish,  $P(\omega_1) + P(\omega_2) = 1$
- Decision without seeing the next fish:
  - ▼ Decide  $\omega_1$  if  $P(\omega_1) > P(\omega_2)$
- For one fish, the above decision is OK, but does not seem right for making multiple decisions on all fish
- Additional information: lightness readings
- Class conditional probability density functions:  $p(x | \omega_1)$  and  $p(x | \omega_2)$

# Hypothetical class conditional densities



Class conditional densities on lightness values

# Bayes Rule

- Suppose the lightness measurement  $x$  is known

$$p(x, \omega_j) = P(\omega_j | x) p(x) = p(x | \omega_j) P(\omega_j)$$

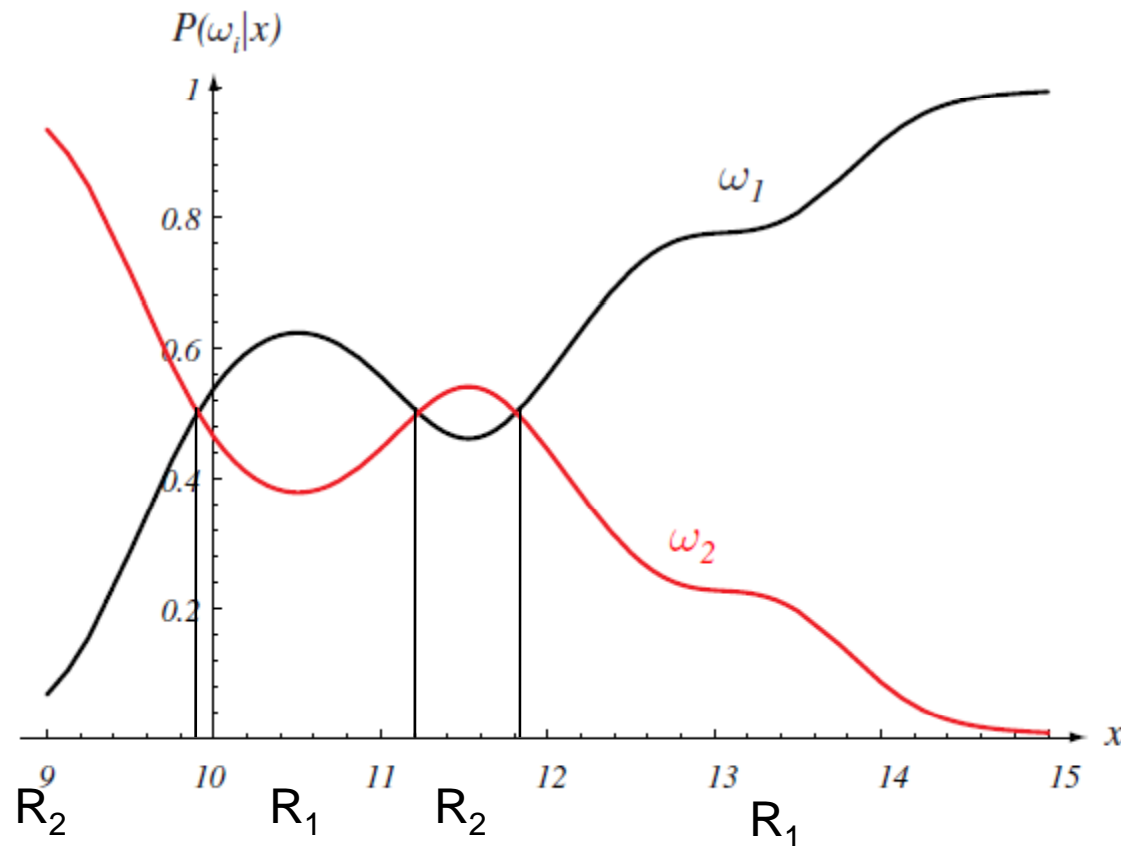
- Bayes Formula:  $P(\omega_j | x) = \frac{p(x | \omega_j) P(\omega_j)}{p(x)}$

- For the 2 category case:  $p(x) = \sum_{j=1}^2 p(x | \omega_j) P(\omega_j)$

- Bayes formula:  $posterior = \frac{likelihood \times prior}{evidence}$

- Decide  $\omega_1$  if  $P(\omega_1|x) > P(\omega_2|x)$

# Posterior Probabilities used for classification



Posterior probabilities for particular priors  $P(\omega_1)=2/3$  and  $P(\omega_2)=1/3$

# Bayesian Decision Theory Extensions

- Minimum error: Decide  $\omega_1$  if  $P(\omega_1|x) > P(\omega_2|x)$
- $P(\text{error})$ :  $P(\omega_2)$  on deciding  $\omega_1$ , and  $P(\omega_1)$  on deciding  $\omega_2$

$$P(\text{error}) = \int_{R_1} P(\omega_2 | x) p(x) dx + \int_{R_2} P(\omega_1 | x) p(x) dx$$

- Extensions

- ▼ More features: d-dimensional feature vector  $x$
- ▼ More categories: c classes -  $\omega_1, \omega_2, \dots, \omega_c$
- ▼ More actions,  $\alpha_1, \alpha_2, \dots, \alpha_a$ , other than merely deciding the state of nature
- ▼ Loss functions,  $\lambda(\alpha_i|\omega_j)$ , more general than error probabilities

# Bayes Rule for the general case

- Posterior probability:  $P(\omega_j | \mathbf{x}) = \frac{p(\mathbf{x} | \omega_j)P(\omega_j)}{p(\mathbf{x})}$
- Evidence:  $p(\mathbf{x}) = \sum_{j=1}^c p(\mathbf{x} | \omega_j)P(\omega_j)$
- Suppose on observing  $\mathbf{x}$ , action  $\alpha_j$  is taken
- However, the true state of nature could be  $\omega_j$
- Conditional risk of taking action  $\alpha_j$  on observing  $\mathbf{x}$   
$$R(\alpha_i | \mathbf{x}) = \sum_{j=1}^c \lambda(\alpha_i | \omega_j)P(\omega_j | \mathbf{x})$$
- Expected Loss/Risk:  $R = \int_{\mathbf{x}} R(\alpha(\mathbf{x}) | \mathbf{x}) p(\mathbf{x}) d\mathbf{x}$
- Minimize expected risk by choosing action  $\alpha(\mathbf{x})$  that minimizes conditional risk
- Bayes Decision Rule: Compute conditional risk for all actions and choose the action that minimizes the conditional risk



# Two category classification

- Loss of taking action  $\alpha_i$  when the true class is  $\omega_j$ :  $\lambda_{ij}$
- Conditional risk of taking the two actions

$$R(\alpha_1 | \mathbf{x}) = \lambda_{11}P(\omega_1 | \mathbf{x}) + \lambda_{12}P(\omega_2 | \mathbf{x})$$

$$R(\alpha_2 | \mathbf{x}) = \lambda_{21}P(\omega_1 | \mathbf{x}) + \lambda_{22}P(\omega_2 | \mathbf{x})$$

- Decide  $\omega_1$  if  $R(\alpha_1|\mathbf{x}) < R(\alpha_2|\mathbf{x})$
- In effect, decide  $\omega_1$  if

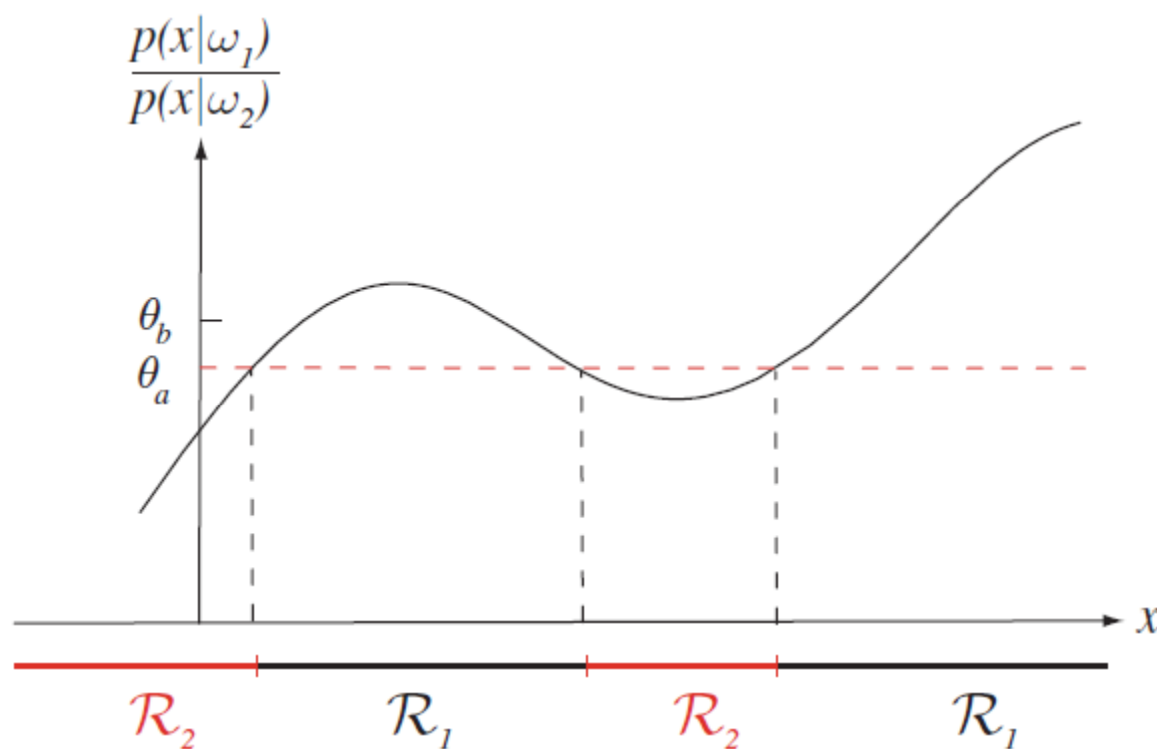
$$(\lambda_{21} - \lambda_{11})P(\omega_1 | \mathbf{x}) > (\lambda_{12} - \lambda_{22})P(\omega_2 | \mathbf{x})$$

$$\text{or, } (\lambda_{21} - \lambda_{11})p(\mathbf{x} | \omega_1)P(\omega_1) > (\lambda_{12} - \lambda_{22})p(\mathbf{x} | \omega_2)P(\omega_2)$$

$$\text{or, } \frac{p(\mathbf{x} | \omega_1)}{p(\mathbf{x} | \omega_2)} > \frac{(\lambda_{12} - \lambda_{22})}{(\lambda_{21} - \lambda_{11})} \frac{P(\omega_2)}{P(\omega_1)}$$

- Likelihood ratio:  $\frac{p(\mathbf{x} | \omega_1)}{p(\mathbf{x} | \omega_2)}$

# Classification using likelihood ratio



# Minimum error rate classification

- Action  $\alpha_i$ : decide  $\omega_i$
- Decision  $\alpha_i$  is correct if true class is  $\omega_i$
- Decision  $\alpha_i$  is incorrect if true class is  $\omega_j, j \neq i$
- Loss function of interest: symmetric zero-one loss function

$$\lambda(\alpha_i | \omega_j) = \begin{cases} 0, & i = j \\ 1, & i \neq j \end{cases}$$

- All errors are equally costly
- Conditional Risk:  $R(\alpha_i | \mathbf{x}) = \sum_{j=1}^c \lambda(\alpha_i | \omega_j) P(\omega_j | \mathbf{x}) = \sum_{j \neq i} P(\omega_j | \mathbf{x}) = 1 - P(\omega_i | \mathbf{x})$
- For min. error, select  $\alpha_i$  that maximizes  $P(\omega_i | \mathbf{x})$
- Decide  $\omega_i$  if  $P(\omega_i | \mathbf{x}) > P(\omega_j | \mathbf{x}), \forall j \neq i$

# Discriminant functions

- Assign  $x$  to class  $\omega_i$  if  $g_i(x) > g_j(x)$ ,  $\forall j \neq i$
- Discriminant functions:  $g_i(x)$
- Examples:
  - ▼  $g_i(x) = P(\omega_i|x)$
  - ▼  $g_i(x) = p(x|\omega_i)P(\omega_i)$
  - ▼  $g_i(x) = \ln p(x|\omega_i) + \ln P(\omega_i)$
  - ▼ Two category case:  $g(x) = g_1(x) - g_2(x)$

# Normal Densities

## ■ Uni-variate Normal:

$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2}\left(\frac{x - \mu}{\sigma}\right)^2\right)$$

$$E(x) = \int xp(x)dx = \mu$$

$$E[(x - \mu)^2] = \sigma^2$$

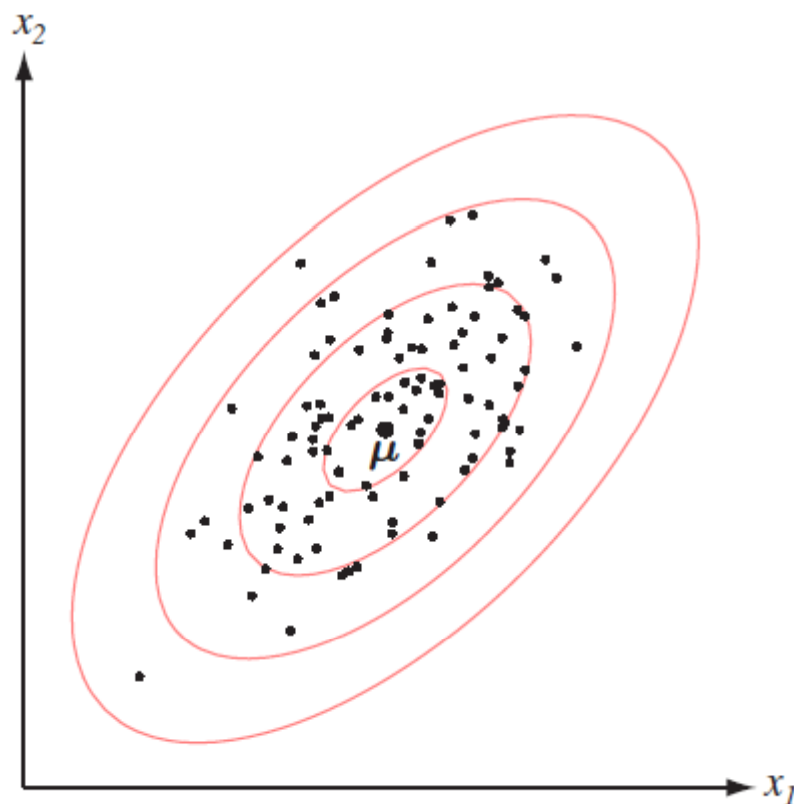
## ■ Multi-variate Normal:

$$p(\mathbf{x}) = \frac{1}{(2\pi)^{d/2} |\boldsymbol{\Sigma}|^{1/2}} \exp\left(-\frac{1}{2}((\mathbf{x} - \boldsymbol{\mu})^T \boldsymbol{\Sigma}^{-1}(\mathbf{x} - \boldsymbol{\mu}))\right)$$

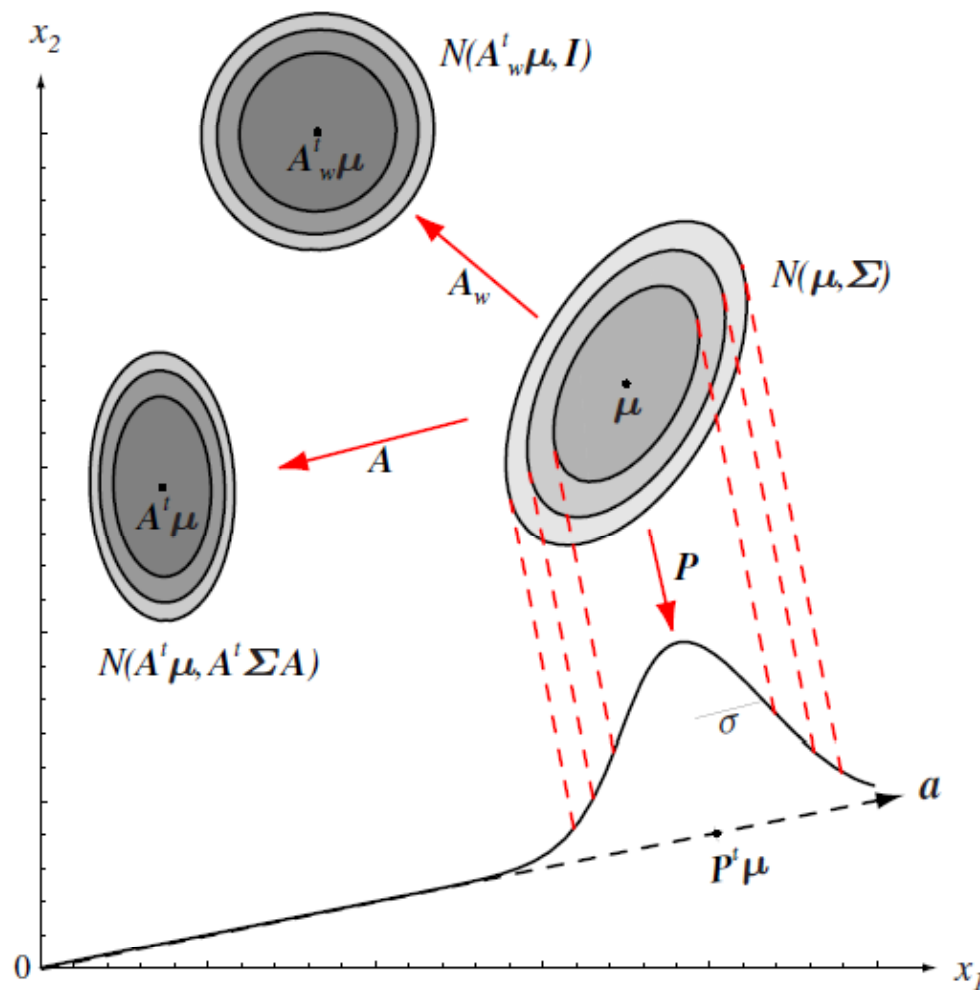
$$\boldsymbol{\mu} = E(\mathbf{x}) = \int \mathbf{x}p(\mathbf{x})d\mathbf{x}$$

$$\boldsymbol{\Sigma} = E[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T] = \int (\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^T p(\mathbf{x})d\mathbf{x}$$

# Samples from a two-dimensional Gaussian density



# Transformations of a Gaussian density



# Two dimensional two-category Gaussian densities

